



- Calibration Assumptions:**
- Weights Are Present
 - Mass of Weights Are Known
 - Operator Has Access to the Calibration Screen of the Dynamometer Controller
 - The Multi-Point Torque Calibration Feature is Enabled within the Dynamometer Controller
 - All Weights and Weight Sets are Configured within the Dynamometer Controller
 - Weight is Hung on the Left Side Calibration Arm (Left vs. Right is Determined by Facing the Dynamometer Side that has been Determined to be the Drive End)
 - If Right Side Calibration is Needed Substitute "Right" for "Left" in Flow Chart