



- Calibration Assumptions:**
- Weights Are Present
  - Mass of Weights Are Known
  - Calibration Arm Length is Known
  - Operator Has Access to the Calibration Screen of the Dynamometer Controller

- Defined Variables:**
- d = Distance From the Center of Shaft to the Weight Hanger Pin
  - T = Computed Simulated Torque
  - W = Calibration Weight